

Customizable Fail-Safe multifunction technology actuator for controlling dampers in typical commercial HVAC applications.

- Torque motor 270 in-lb [30 Nm]
- Nominal voltage AC/DC 24 V
- Control MFT/programmable
- Position feedback 2...10 V
- 2 x SPDT





EFX24-MFT-S

5-year warranty





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Technical data

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Nominal voltage	AC/DC 24 V	
Nominal voltage frequency	50/60 Hz	
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V	
Power consumption in operation	9.5 W	
Power consumption in rest position	4.5 W	
Transformer sizing	16 VA	
Auxiliary switch	2 x SPDT, 1 mA3 A (0.5 A inductive), DC 5 VAC 250 V, one set at 10°, one adjustable 1090°	
Switching capacity auxiliary switch	1 mA3 A (0.5 A inductive), DC 5 VAC 250 V	
Electrical Connection	(2) 18 GA appliance cables, 1 m, 3 m or 5 m, with or without 1/2" conduit connectors	
Overload Protection	electronic throughout 095° rotation	
Electrical Protection	actuators are double insulated	
Torque motor	270 in-lb [30 Nm]	

Functional data

Electrical Protection	actuators are double insulated
Torque motor	270 in-lb [30 Nm]
Operating range Y	210 V
Operating range Y note	420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)
Input impedance	100 k Ω for 210 V (0.1 mA), 500 Ω for 420 mA, 1500 Ω for PWM, On/Off and Floating point
Operating range Y variable	Start point 0.530 V End point 2.532 V
Operating modes optional	variable (VDC, PWM, on/off, floating point)
Position feedback U	210 V
Position feedback U note	Max. 0.5 mA
Position feedback U variable	VDC variable
Direction of motion motor	selectable with switch 0/1
Direction of motion fail-safe	reversible with cw/ccw mounting
Manual override	5 mm hex crank (3/16" Allen), supplied
Angle of rotation	Max. 95°
Angle of rotation note	adjustable with mechanical end stop, 3595°
Running Time (Motor)	150 s / 90°
Running time motor variable	60150 s
Running time fail-safe	<20 s @ -4122°F [-2050°C], <60 s @ -22°F [-30°C]
Adaptation Setting Range	off (default)
Override control	MIN (minimum position) = 0% MID (intermediate position) = 50% MAX (maximum position) = 100%
Noise level, motor	45 dB(A)
Noise level, fail-safe	71 dB(A)



Technical data sheet	EFX24-MFT	
Position indication	Mechanical	
Power source UL	Class 2 Supply	
Degree of protection IEC/EN	IP54	
Degree of protection NEMA/UL	NEMA 2	
Enclosure	UL Enclosure Type 2	
Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02	
	CE acc. to 2014/30/EU and 2014/35/EU	
Quality Standard	ISO 9001	
UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC	
Ambient humidity	Max. 95% RH, non-condensing	
Ambient temperature	-22122°F [-3050°C]	
Storage temperature	-40176°F [-4080°C]	

maintenance-free

12 lb [5.3 kg]

Weight

Materials

Servicing

Weight

Functional data

Safety data

Housing material Die cast aluminium and plastic casing

Footnotes

*Variable when configured with MFT options.

†Rated Impulse Voltage 800V, Type of Action 1.AA.B, Control Pollution Degree 3.

Product features

Default/Configuration

Default parameters for 2 to 10 VDC applications of the EF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication or primary and secondary applications. Two EF's can be piggybacked for torque loads of up to 540 in-lbs. Minimum 3/4" diameter shaft. OR Maximum of three EF's can be piggybacked for torque loads of up to 810 in-lbs. Minimum 1" diameter shaft. primary and secondary wiring for either configuration.



Operation

The EF..24-MFT actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The EF..24-MFT is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The EF..24-MFT actuator is shipped at 5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Installation Note: Use flexible metal conduit. Push the UL listed conduit fitting device over the actuator's cable to butt against the enclosure. Screw in conduit connector. Jacket the actuator's input wiring with UL listed flexible conduit. Properly terminate the conduit in a suitable junction box.

Typical specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback or primary and secondary applications. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Factory settings

Default parameters for 2 to 10 VDC applications of the EF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Accessories

Electrical accessories	Description	Туре
	DC Voltage Input Rescaling Module	IRM-100
	Auxiliary switch, mercury-free	P475
	Auxiliary switch, mercury-free	P475-1
	Convert Pulse Width Modulated Signal to a 210 V Signal for Belimo	PTA-250
	Proportional Actuators	
	Positioner for wall mounting	SGA24
	Positioner for front-panel mounting	SGF24
	Cable conduit connector 1/2"	TF-CC US
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to LonWorks	UK24LON
	Gateway MP to Modbus RTU	UK24MOD
	Resistor, 500 Ω , 1/4" wire resistor with 6" pigtail wires	ZG-R01
	Resistor kit, 50% voltage divider	ZG-R02
	Transformer, AC 120 V to AC 24 V, 40 VA	ZG-X40



Technical data sheet EFX24-MF

Mechanical accessories

Description	Туре
Shaft extension 240 mm ø20 mm for damper shaft ø822.7 mm	AV8-25
Anti-rotation bracket EFB(X)/GKB(X)/GMB(X).	EF-P
End stop indicator	IND-EFB
Shaft clamp reversible, clamping range ø1226.7 mm	K9-2
Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A
Damper crank arm Slot width 8.2 mm, clamping range ø1425 mm	KH10
Actuator arm Slot width 8.2 mm	KH-EFB
Push rod for KG10A ball joint 36" L, 3/8" diameter	SH10
Wrench 0.512 in. [13 mm]	TOOL-07
Mounting bracket for AF	ZG-100
Jackshaft mounting bracket.	ZG-120
ZG-JSL support plate for EFB(X)	ZG-121
Damper clip for damper blade, 3.5" width.	ZG-DC1
Damper clip for damper blade, 6" width.	ZG-DC2
Mounting kit for linkage operation for flat and side installation	ZG-EFB
1.05" diameter jackshaft adaptor (12" L).	ZG-JSA-3
Description	Туре
Connecting cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
Connecting cable 16 ft [5 m], A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN
Service Tool, with ZIP-USB function, for programmable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH US
Belimo PC-Tool, Software for adjustments and diagnostics Signal simulator, Power supply AC 120 V	MFT-P PS-100

Electrical installation



Tools

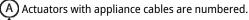
/\ Warning! Live electrical components!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground connection.

Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches. Mixed or combined operation of line voltage/safety extra low voltage is not allowed.



Provide overload protection and disconnect as required.

Actuators may also be powered by DC 24 V.

Two built-in auxiliary switches (2x SPDT), for end position indication, interlock control, fan startup, etc.

6 Only connect common to negative (-) leg of control circuits.

 Λ A 500 Ω resistor (ZG-R01) converts the 4...20 mA control signal to 2...10 V.

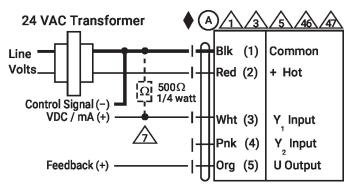
Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 V line. A For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the

actuator internal common reference is not compatible.

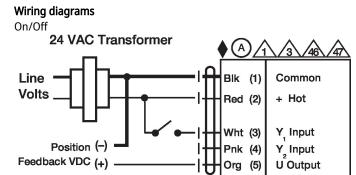
🔼 IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).

Actuators may be controlled in parallel. Current draw and input impedance must be observed. Master-Slave wiring required for piggy-back applications. Feedback from Master to control input(s) of Slave(s).

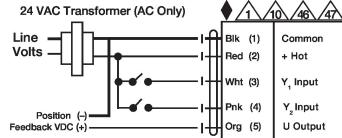




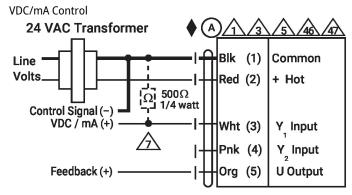
VDC/mA Control

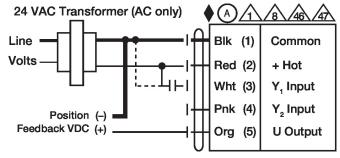




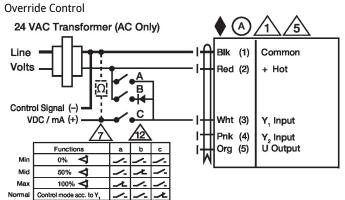


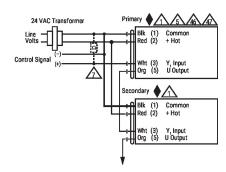
PWM Control



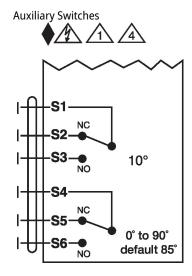


Primary - Secondary





Technical data sheet



Dimensions

