

## Butterfly Valve with Lug types

- Disc 304 stainless steel
- Bubble tight shut-off
- Resilient seat
- Valve face-to-face dimensions comply with API 609 & MSS-SP-67
- Completely assembled and tested, ready for installation



2-year warranty

## Type overview

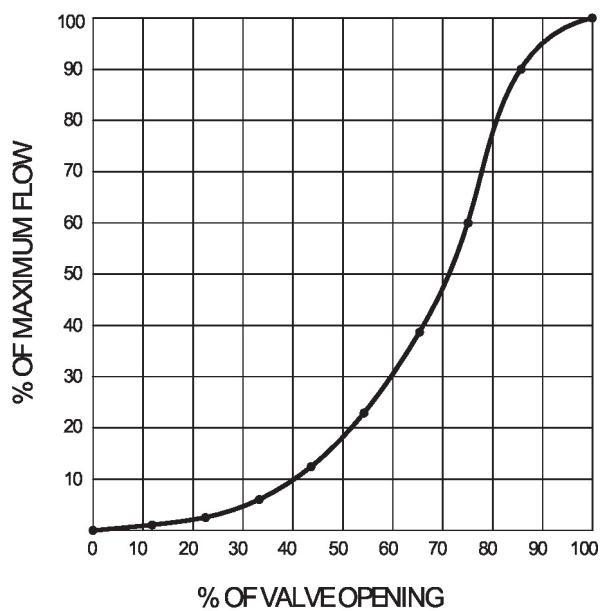
Type	DN
F6350HD	350

## Technical data

Functional data	Valve size [mm]	14" [350]
Fluid	chilled or hot water, up to 60% glycol	
Fluid Temp Range (water)	-22...250°F [-30...120°C]	
Body Pressure Rating	ANSI Class Consistent with 125, 232 psi CWP	
Close-off pressure Δps	150 psi	
Flow characteristic	modified equal percentage	
Leakage rate	0% leakage, leakage rateA	
Pipe connection	Flange for use with ASME/ANSI class 125/150	
Servicing	maintenance-free	
Flow Pattern	2-way	
Controllable flow range	90° rotation	
Cv	11917	
Maximum Velocity	12 FPS	
Lug threads	1-8 UNC	
Materials	Valve body	Ductile cast iron ASTM A536
	Body finish	epoxy powder coating (blue RAL 5002)
	Stem	416 stainless steel
	Stem seal	EPDM (lubricated)
	Seat	EPDM
	Bearing	RPTFE
	Disc	304 stainless steel
Suitable actuators	Non Fail-Safe	SY5

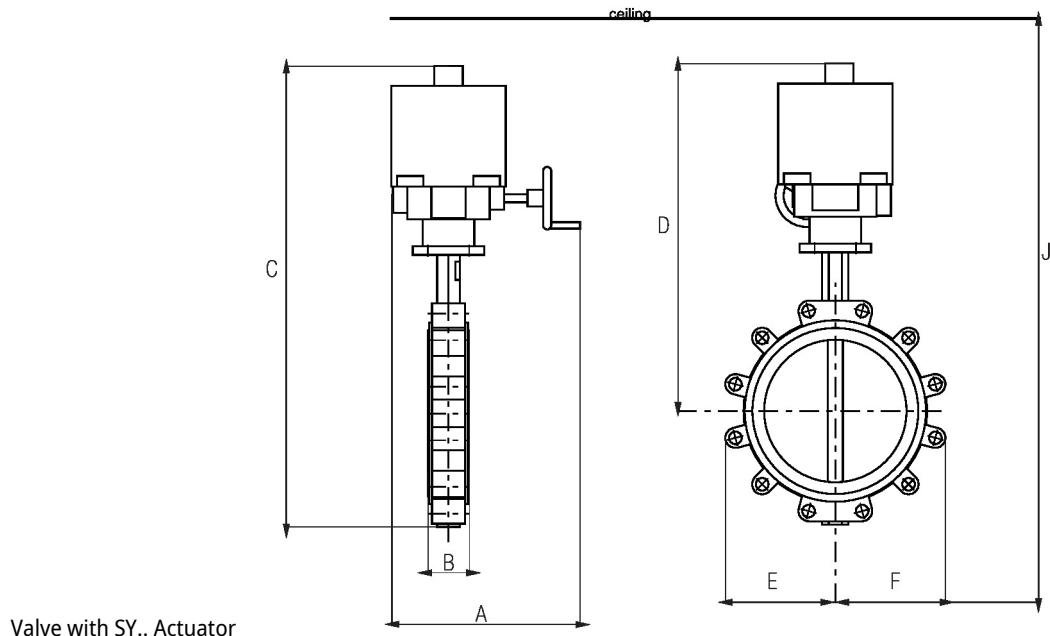
## Product features

## Flow/Mounting details



## Dimensions

Type	DN	Weight
F6350HD	350	280 lb [130 kg]



A	B	C	D	E	F	J	Number of Bolt Holes
11.5" [293]	3.2" [82]	37.6" [955]	27.2" [691]	10.2" [260]	10.2" [260]	45.7" [1161]	12

On/Off, Floating point, Non fail-safe, 24 V



2-year warranty

## Technical data

Electrical data		
Nominal voltage	AC/DC 24 V	
Nominal voltage frequency	50/60 Hz	
Nominal voltage range	AC 21.6...26.4 V / DC 21.6...26.4 V	
Transformer sizing	214 VA	
Current consumption	8.9 A	
Auxiliary switch	2x SPDT, 1 mA...5 A (3 A inductive), DC 5 V...AC 250 V, 1 x 3° / 1 x 87°	
Switching capacity auxiliary switch	1 mA...5 A (3 A inductive), DC 5 V...AC 250 V	
Electrical Connection	Terminal blocks	
Overload Protection	thermally protected 135°C cut-out	
Internal Humidity Control	resistive heating element	
Functional data		
Torque motor	500 Nm	
Direction of motion motor	selectable with switch 0/1	
Manual override	hand wheel	
Angle of rotation	90°	
Running Time (Motor)	26 s	
Duty cycle value	30%	
Noise level, motor	45 dB(A)	
Position indication	top mounted domed indicator	
Safety data		
Degree of protection IEC/EN	IP66/67	
Degree of protection NEMA/UL	NEMA 4X	
Enclosure	UL Enclosure Type 4X	
Agency Listing	ISO, CE, cCSAus	
Quality Standard	ISO 9001	
Ambient humidity	Max. 100% RH	
Ambient temperature	-22...149°F [-30...65°C]	
Storage temperature	-40...176°F [-40...80°C]	
Servicing	maintenance-free	
Weight		
Weight	46 lb [21 kg]	
Materials		
Housing material	die cast aluminium	
Gear train	high alloy steel gear sets, self locking	

## Product features

**Application** SY Series actuators are fractional horsepower devices, and utilize full-wave power supplies. Observe wire sizing and transformer sizing requirements. Proportional models CANNOT be connected to Belimo direct coupled (AF, AM, GM...etc) actuator power supplies or any type of half-wave device. You MUST use a separate, dedicated transformer or power supply to power the SY actuator. Please do not connect other automation equipment to the dedicated SY supply source. You MUST use four wires (plus a ground) to control a proportional control SY actuator (See SY Wiring Section).

## Accessories

Electrical accessories	Description	Type
	Local electric disconnect for SY4...12 series actuator, AC 120 V, on/off	HOA-120V
	Battery backup system for SY4...6 series actuator, AC 120 V, on/off	EXT-NSV-B03-120
	Battery backup system for SY4...6 series actuator, AC 120 V, MFT	EXT-NSV-B04-120
	Battery backup system for SY4...5 series actuator, AC 24 V, on/off	EXT-NSV-B13-24
	Battery backup system for SY4...5 series actuator, AC 24 V, MFT	EXT-NSV-B14-24

## Electrical installation

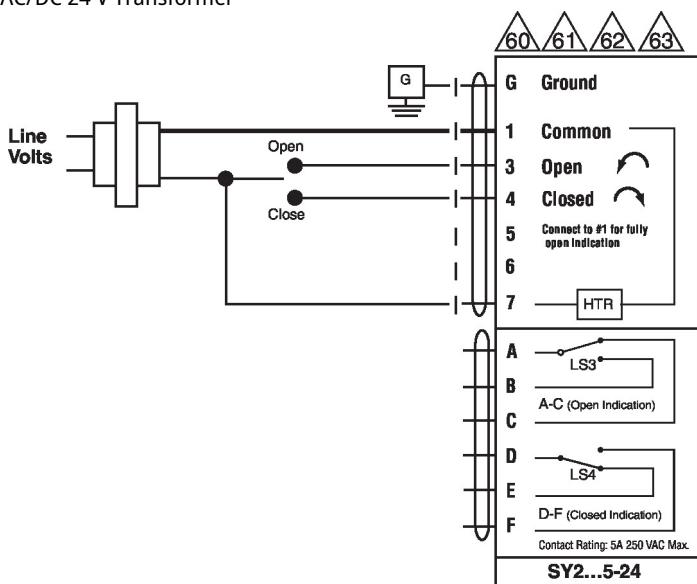
 **INSTALLATION NOTES**

-  Do not change sensitivity or dip switch setting with power applied.
-  Power supply Common/Neutral and Control Signal "-"wiring to a common is prohibited. Terminals 4 and 6 need to be wired separately.
-  Isolation relays must be used in parallel connection of multiple actuators using a common control signal inputs. The relays should be DPDT.
-  Isolation relays are required in parallel applications. The reason parallel applications need isolation relays is that the motor uses two sets of windings, one for each direction. When one is energized to turn the actuator in a specific direction a voltage is generated in the other due to the magnetic field created from the first. It's called back EMF. This is not an issue with one actuator because the voltage generated in the second winding isn't connected to anything so there is no flow. On parallel applications without isolation, this EMF voltage energizes the winding it is connected to on the other actuators in the system, the actuators are trying to turn in both directions at once. The EMF voltage is always less than the supply voltage due to the resistance of the windings, so while the actuator still turns in the commanded direction, the drag from the other reduces the torque output and causes overheating.
-  **Warning! Live electrical components!**  
During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

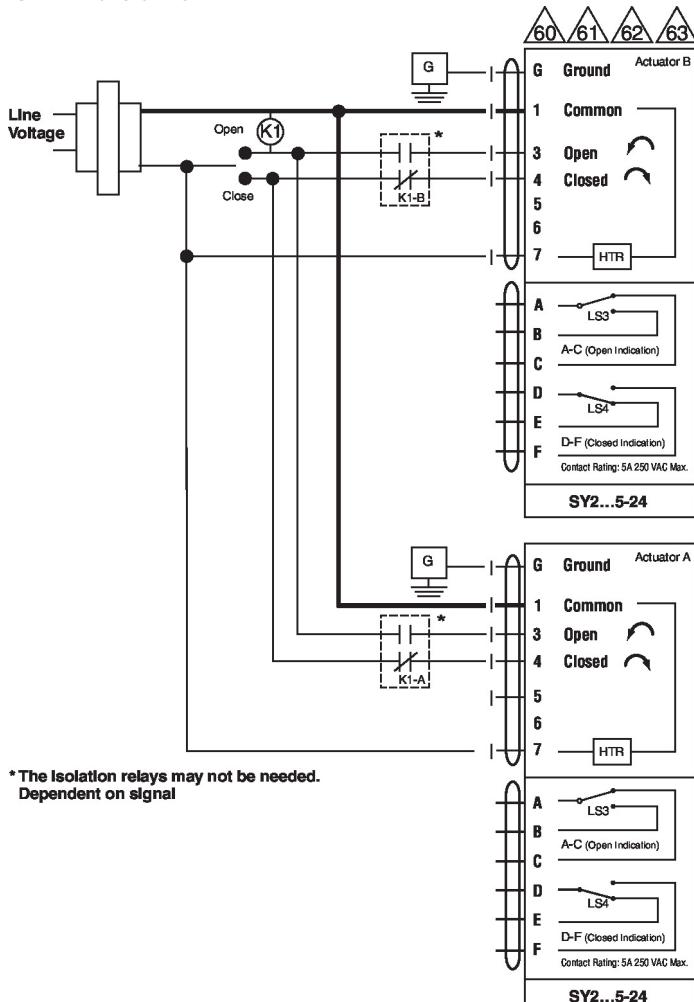
## Electrical installation

## Wiring diagrams

AC/DC 24 V Transformer



AC 24 V Transformer



\* The isolation relays may not be needed.  
Dependent on signal